Fluid Dynamics



- The study of fluid mechanics in which the forces and energies are considered along with the motion.
- Types of forces
 - Body forces proportional to volume or weight

e.g. centrifugal, magnetic, gravity etc.

- ✓ Surface forces proportional to area e.g. pressure, shear or tangential forces
- ✓ Line forces proportional to length e.g. surface tension
- Similar to solid mechanics fluid dynamics is also governed by Newton's second law of motion.

Newton's Second law and Fluid



 Resultant force on any fluid element must be equal to the product of mass and the acceleration the element in the same direction



a is the acceleration of fluid particle, F is the total force acting on fluid particle and ρ is the mass density; x, y and z indicate the suffix for the components along respective directions

- Gravity Force F_g = Mg
- Pressure Force, F_p
- Viscous force, F_v
- Turbulent Force, F_t
- Surface Tension, F_s
- Compressibility Force, F_e

$$Ma = F_g + F_p + F_v + F_t + F_s + F_e$$
$$Ma_x = F_{gx} + F_p x + F_{vx} + F_{tx} + F_{sx} + F_{ex}$$
$$Ma_y = F_{gxy} + F_{py} + F_{vy} + F_{ty} + F_{sy} + F_{ey}$$
$$Ma_z = F_{gz} + F_{pz} + F_{vz} + F_{tz} + F_{sz} + F_{ez}$$

Reynolds Equations of fluid motion

For fluid in motion the forces due to surface tension and the compressibility effects are negligible



These equations are useful for the analysis of turbulent flow

Navier-Stokes Equations



For laminar or viscous flow the forces due to turbulence are negligible



These equations are useful for the analysis of laminar flow

Euler's Equations for fluid flow

For ideal fluid flow the viscous forces are negligible

$$Ma = F_g + F_p$$
$$Ma_x = F_{gx} + F_p x$$
$$Ma_y = F_{gxy} + F_{py}$$
$$Ma_z = F_{gz} + F_{pz}$$

The Euler's equation is comprised of only body and surface forces

These equations are useful if the viscosity of the fluid is negligible or insignificant.



- Let X, Y and Z be the components of body forces per unit mass at point P
- Mass of parallelepiped = $(\rho \delta x \delta y \delta z)$
- Total component of body force in X-dirⁿ = X (ρδxδyδz)
- Total component of body force in Y-dirⁿ = Y (ρδxδyδz)
- Total component of body force in Z-dirⁿ = Z ($\rho\delta x\delta y\delta z$)
- Pressure intensity at P = p
- Total pressure force acting on PQRS = p ($\delta y \delta z$)
- Pressure intensity on P'Q'R'S' = $p + \frac{\partial p}{\partial x} \delta x$
- Total pressure force acting on PQRS = $(p + \frac{\partial p}{\partial p} \delta x) \delta y \delta z$

Net pressure force in X-dirⁿ

Similarly,

$$F_{py} = -\frac{\partial p}{\partial y} \delta x \delta y \delta z$$
 and $F_{pz} = -\frac{\partial p}{\partial z} \delta x \delta y \delta z$

Adding body forces and pressure forces in X-direction and equating to the product of mass and acceleration in X-direction

$$X(\rho \delta x \delta y \delta z) - \frac{\partial p}{\partial x} \delta x \delta y \delta z = \rho(\delta x \delta y \delta z) a_x - - - \mathbf{A}$$

• Thus

$$X - \frac{1}{\rho} \frac{\partial p}{\partial x} = a_x$$
• Similarly,

$$Y - \frac{1}{\rho} \frac{\partial p}{\partial y} = a_y$$
Euler's equations of fluid motion

$$Z - \frac{1}{\rho} \frac{\partial p}{\partial z} = a_z$$
Where,

$$a_x = \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}$$

$$a_y = \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z}$$

$$a_z = \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z}$$

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + X$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial y} + Y$$

$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial z} + Z$$

No assumption that p is constant is made in these equations, therefore these are applicable to compressible or incompressible, non-viscous fluid flow in steady as well as unsteady state

- Gives energy equation under following assumptions
- 1. There exists a force potential which is defined as the function whose negative derivative wrt any direction gives the component of body force per unit mass in that direction (Ω). Thus,

$$X = -\frac{\partial \Omega}{\partial x} \quad Y = -\frac{\partial \Omega}{\partial y} \quad Z = -\frac{\partial \Omega}{\partial z}$$

2. The flow is irrotational i.e. velocity potential exists or the flow may be rotational but it's steady

When flow is irrotational

Consider Euler's equation in X-direction

$$X - \frac{1}{\rho} \frac{\partial p}{\partial x} = \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}\right)$$

If flow is irrotational $\longrightarrow \frac{\partial u}{\partial y} = \frac{\partial v}{\partial x}; \frac{\partial u}{\partial z} = \frac{\partial w}{\partial x}$
•Existence of velocity potential $\longrightarrow u = -\frac{\partial \phi}{\partial x}$

Therefore,
$$-\frac{\partial\Omega}{\partial x} - \frac{1}{\rho}\frac{\partial p}{\partial x} = -\frac{\partial^2 \phi}{\partial x \partial t} + u\frac{\partial u}{\partial x} + v\frac{\partial v}{\partial x} + w\frac{\partial w}{\partial x}$$

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 $\frac{\partial}{\partial x} \left[\Omega + \frac{p}{\rho} + \frac{u^2 + v^2 + w^2}{2} - \frac{\partial \phi}{\partial t} \right] = 0$

On integrating wrt x

Thus,

$$\left[\Omega + \frac{p}{\rho} + \frac{V^2}{2} - \frac{\partial \phi}{\partial t}\right] = F_1(y, z, t)$$

Similarly, for Y and Z directions

$$\left[\Omega + \frac{p}{\rho} + \frac{V^2}{2} - \frac{\partial \phi}{\partial t}\right] = F_2(x, z, t)$$

$$\left[\Omega + \frac{p}{\rho} + \frac{V^2}{2} - \frac{\partial \phi}{\partial t}\right] = F_3(x, y, t)$$

hus,
$$F_1(y, z, t) = F_2(x, z, t) = F_3(x, y, t)$$

Since x, y and z are the independent variables the above equation will hold good only if these variables disappear from functional term and F is only function of t

Therefore,
$$\left[\Omega + \frac{p}{\rho} + \frac{V^2}{2} - \frac{\partial \phi}{\partial t}\right] = F(t)$$

$$\left[\Omega + \frac{p}{\rho} + \frac{V^2}{2}\right] = 0$$

If the body force exerted on the fluid is only due to gravity and if Z axis is so oriented that z is measured in vertical direction with reference to datum then,

$$-\frac{\partial\Omega}{\partial x} = 0; -\frac{\partial\Omega}{\partial y} = 0; -\frac{\partial\Omega}{\partial z} = -g$$

Since g is the force per unit mass and can be +ve when acting in downward direction $\Omega = gz + C_1$ At z = 0 Ω = 0, therefore C₁ = 0

Therefore,
$$\Omega = gz$$

$$\left[\frac{p}{\rho} + \frac{V^2}{2} + gz\right] = C$$

Bernoulli's Equation



 $\left| \frac{p}{\rho g} + \frac{V^2}{2g} + z \right| = C$ \Box Energy Equation as each term indicates energy per unit weight



Each term also indicate the head e.g. pressure, velocity and potential head

Thus, the Bernoulli's theorem states that for steady flow of an incompressible fluid the total energy which is the summation of pressure, velocity and potential energy remains constant at any point



 $\mathcal{Z} \longrightarrow$ Potential head or datum head

$$\left(\frac{p}{w}+z\right)$$
 \longrightarrow Piezometric head

$$\left[\frac{p_1}{w} + \frac{V_1^2}{2} + z_1\right] = \left[\frac{p_2}{w} + \frac{V_2^2}{2} + z_2 + h_L\right]$$

- When flow is rotational but steady
- Consider an element of stream filament of CSA δa



- Let S be the body force per unit mass along streamline
- Mass of fluid element = $(\rho \delta a \delta s)$
- Total body force along S-direction = S (ρδa δs)
- Total pressure force on left end = pδa
- Total pressure force on right end = [p+(∂p/∂s) δs] δa

$$F_{ps} = \left[(p\delta a) - (p + \frac{\partial p}{\partial s}\delta s)\delta a \right] = -\frac{\partial p}{\partial s}\delta s\delta a$$

Steady flow acceleration

$$a_s = V \frac{\partial V}{\partial s} = \frac{1}{2} \frac{\partial V^2}{\partial s}$$

Newton's second law of motion

$$S(\rho\delta s\delta a) - \frac{\partial p}{\partial s}\delta s\delta a = (\rho\delta s\delta a)\frac{1}{2}\frac{\partial V^2}{\partial s}$$

$$S = -\frac{\partial \Omega}{\partial s}$$

Therefore,

 $\Omega = gz$

$$\frac{\partial \Omega}{\partial s} + \frac{1}{\rho} \frac{\partial p}{\partial s} + \frac{1}{2} \frac{\partial V^2}{\partial s} = 0$$

$$\Omega + \frac{p}{\rho} + \frac{V^2}{2} = C$$

For incompressible flow

For compressible flow

$$\Omega + \int \frac{\partial p}{\rho} + \frac{V^2}{2} = C$$

$$\frac{p}{\rho} + \frac{V^2}{2} + gz = C$$
 or $\frac{p}{w} + \frac{V^2}{2} + z = C$

Euler's Equation – an important point

□If the flow is irrotational then the same Bernoulli's equation is applicable to all the points in the flow field i. e. for all the streamlines the value of constant is same.

For rotational flow the Bernoulli's equation is applicable for a particular streamline i. e. the value of constant is different for different streamlines

Bernoulli's Equation- Principle of conservation of energy



Figure:- Free body of flowing fluid occupying a portion of stream tube between two arbitrarily chosen sections 1-1 and 2-2

The general energy equation

work done on the fluid			Mechanical work		
by force during dt			$^{\pm}$ [performed on the fluid		
	Total energy of fluid	[Total energy of fluid $]$		
=	between	_	between		
	$\begin{bmatrix} 1 & -1 \end{bmatrix}$ and $2 & -2 \end{bmatrix}$ at $t_2 \end{bmatrix}$		1-1 and 2-2 at t_2		

• But

Total energy of fluid Tot		Гota	tal energy of fluid			Total energy of fluid		
between =		between	+		between			
$\begin{bmatrix} 1' - 1' \text{ and } 2' - 2' \text{ at } \mathbf{t}_2 \end{bmatrix}$			1'-1' and 2-2 at t_2		2-2 and $2'-2'$ at t_2			
	Total energy of fluid		Total energy of fluid			Total energy of fluid		
and	between =		between			between		
	$\begin{bmatrix} 1-1 \text{ and } 2-2 \text{ at } t_1 \end{bmatrix}$		1-1 and 1'-1' at t ₁			$\begin{bmatrix} 1 & -1 & \text{and } 2-2 \text{ at } t_1 \end{bmatrix}$		

For steady flow the state of the flowing fluid in the stream tube within the region bounded by sections 1'-1' and 2-2 remains unchanged wrt to time. Thus,

Total energy of fluid		Total energy of fluid
between	=	between
$[1' - 1' \text{ and } 2 - 2 \text{ at } t_2]$		1'-1' and 2-2 at t ₁

Hence the general energy equation for steady flow of fluid is

reduced to

work done on the fluid				[Mechanical work]	
by external forces during				performed on the	
d	t		fluid		
	Total energy of		Total energy of		
=	fluid between	_	flu	uid between	
	$2 - 2$ and $2' - 2'$ at t_{2}		_1-1	and $1'-1'$ at t_1	

 For steady flow the mass flow at sections 1-1 and 2-2 during dt being same

Fluid mass between]=	Fluid mass between		
1 -1 and 1 -1		2 -2 and $2'-2'$		

Work done by pressure force $(p_1 dA_1)$ on the free body of the fluid in the stream tube during dt is + $(p_1 dA_1)(V_1 dt)$

Work done by pressure force $(p_2 dA_2)$ on the free body of the fluid in the stream tube during *dt* is - $(p_2 dA_2)(V_2 dt)$

Net work done performed by pressure forces on the free body of the fluid in the stream tube during dt is $[(p_1dA_1)(V_1dt) - (p_2dA_2)(V_2dt)]$

If dm is the total mass of fluid flowing across section 1-1 during dt or if dm is actually the mass of fluid within 1-1 and 1'-1' or between 2-2 and 2'-2', then

$$(V_1 dA_1)dt = \frac{dm}{\rho_1}; \text{ and } (V_2 dA_2)dt = \frac{dm}{\rho_2}$$

Thus net work done by pressure forces on the free body of fluid is

$$\left(\frac{p_1}{\rho_1} - \frac{p_2}{\rho_2}\right) dm$$

Total work done by the fluid or on the fluid by external device is $\pm h_m gdm$

- Gravitational potential energies are given as z₁gdm and z₂gdm and net potential energy is (z₁-z₂)gdm
- Kinetic energies are $(V_1^2/2)dm$; $(V_2^2/2)dm$ and net KE

 $dm(V_1^2 - V_2^2)/2)$

Thus, general energy equation is given as

$$\left(\frac{p_1}{\rho_1} - \frac{p_2}{\rho_2}\right) dm \pm h_m g dm = (z_2 - z_1) g dm + \frac{dm}{2} (V_2^2 - V_1^2)$$

$$\frac{p_1}{\rho} + \frac{V_1^2}{2} + gz_1 = \frac{p_2}{\rho} + \frac{V_2^2}{2} + gz_2 \pm h_L$$

$$\frac{p_1}{w} + \frac{V_1^2}{2g} + z_1 = \frac{p_2}{w} + \frac{V_2^2}{2g} + z_2 \pm h_L$$

$$\frac{p_1}{w} + \frac{V_1^2}{2g} + z_1 =$$
constant

This equation is applicable to the steady flow of an incompressible fluid

Kinetic energy correction factor

- Velocity is assumed to be uniform over the entire cross-section in the derivation of BE
- KE at any section can be obtained by integration of KE of all the particles over the cross section
- If v is the local velocity through dA (a small area along cross section), the mass flow = ρvdA
- KE of fluid passing through $dA = (\rho v dA)v^2/2$
- Total KE possessed by the flowing fluid across entire cross section A is

$$\int_{A} \rho \frac{v^{3}}{2} dA = \frac{w}{2g} \int_{A} v^{3} dA$$

 Convenient way to express KE is with the help of mean velocity of flow (V).

Kinetic energy correction factor

- However, the actual KE is greater than the KE computed using mean velocity (V)
- Hence the factor α is introduced such that KE is

Actual KE =
$$\alpha \frac{w}{2g} AV^3$$

Thus,

$$\alpha \frac{w}{2g} A V^3 = \frac{w}{2g} \int_A v^3 dA \qquad \Longrightarrow \qquad \alpha = \frac{1}{A V^3} \int_A v^3 dA$$

• Mathematically, the cube of average is less than the average of cubes i.e. $V^3 < \frac{1}{A} \int_A v^3 dA$ α is always greater than 1

Kinetic energy correction factor

- For turbulent flow α lies between 1.03 to 1.06 which is close to 1.
- For laminar flow in pipes it is 2.
- The KE in BE can be introduced as

$$\frac{p_1}{w} + \alpha_1 \frac{V_1^2}{2g} + z_1 = \frac{p_2}{w} + \alpha_2 \frac{V_2^2}{2g} + z_2 + h_L$$

Assignment – Prove that for laminar flow $\alpha = 2$

$$\int \frac{dp}{\rho} + \frac{V^2}{2} + gz = C$$

Isothermal Change $\rho = p/K$

$$\frac{p}{\rho} = K \text{ or } \frac{p}{\rho g} = K'$$

Substitute the value of ρ and integrate the pressure term

$$K \log_e p + \frac{V^2}{2} + gz = C$$
 or $gK' \log_e p + \frac{V^2}{2} + gz = C$

$$K \log_e p_1 + \frac{V_1^2}{2} + gz_1 = K \log_e p_2 + \frac{V_2^2}{2} + gz_2$$

$$gK' \log_e p_1 + \frac{V_1^2}{2} + gz_1 = gK' \log_e p_2 + \frac{V_2^2}{2} + gz_2$$

$$K \log_e(p_1 / p_2) = \frac{V_2^2}{2} - \frac{V_1^2}{2} + g(z_2 - z_1)$$

$$K' \log_e(p_1 / p_2) = \frac{V_2^2}{2g} - \frac{V_1^2}{2g} + (z_2 - z_1)$$

$$\int \frac{dp}{\rho} + \frac{V^2}{2} + gz = C$$

Adiabatic change

$$\frac{p}{\rho^k} = C_1; \text{ or } \frac{p}{(\rho g)^k} = C_1'$$

k is the exponent of adiabatic change

$$\frac{dp}{d\rho} = C_1 k \rho^{k-1}; \text{ or } \frac{dp}{\rho} = C_1 k \rho^{k-2} d\rho \quad \frac{dp}{d\rho} = C_1 g^k k \rho^{k-1}; \text{ or } \frac{dp}{\rho} = C_1 g^k k \rho^{k-2} d\rho$$

$$C_1 k \frac{\rho^{k-1}}{(k-1)} + \frac{V^2}{2} + gz = C$$

$$C_{1}g^{k}k\frac{\rho^{k-1}}{(k-1)}+\frac{V^{2}}{2}+gz=C$$

Adiabatic change

$$C_1 k \frac{\rho^{k-1}}{(k-1)} + \frac{V^2}{2} + gz = C$$

$$\frac{k}{k-1}\frac{p}{\rho} + \frac{V^2}{2} + gz = C$$

$$C_{1}'g^{k}k\frac{\rho^{k-1}}{(k-1)} + \frac{V^{2}}{2} + gz = C$$

$$\frac{k}{k-1}\frac{p}{w} + \frac{V^2}{2g} + z = C'$$

Applications of Bernoulli's Equation

Discharge measurement Venturi meter Orifice meter Nozzle meter Rota meter Elbow meter velocity measurement Pitot tube

The other important equation used in these applications is continuity equation
> a device for measuring a flow rate through a pipe

➤G B Venturi – an Italian Physicist (1797)

Principle – reduction in cross-sectional area of flow passage creates pressure difference which enables flow measurement



- Convergent cone angle -21°±1; length 2.7(D-d)
- Throat length is d, diameter of throat is 1/3 to ³/₄ of dia of pipe
 - Diameter of throat is restricted by a cavitation
- Divergent cone angle 5° to 15° (preferably 6°)

 length is much larger than convergent cone to avoid separation

- Let a₁ and a₂ be the cross sectional area of inlet section and sections at 2, respectively; p₁ and p₂ be corresponding pressures; V₁ and V₂ are respective velocities.
- Bernoulli's equation between 1 and 2 gives

$$\frac{p_1}{w} + \frac{V_1^2}{2g} + z_1 = \frac{p_2}{w} + \frac{V_2^2}{2g} + z_2$$

• If Venturi is horizontal $z_1 = z_2$



Represents difference in pressure heads between inlet and throat which is known as Venturi head and denoted by h

Therefore,
$$h = \frac{V_2^2}{2g} - \frac{V_1^2}{2g}$$

Continuity equation,

$$Q_{th} = a_1 V_1 = a_2 V_2 \longrightarrow V_1 =$$

$$= \frac{Q_{th}}{a_1}$$
 and $V_2 = \frac{Q_{th}}{a_2}$

$$h = \frac{Q_{th}}{2g} \left[\frac{1}{a_2^2} - \frac{1}{a_1^2} \right] \longrightarrow Q_{th} = \frac{a_1 a_2 \sqrt{2gh}}{\sqrt{a_1^2 - a_2^2}}$$

Coefficient of Discharge for Venturi Meter

 Actual discharge is always less than the theoretical discharge and hence actual discharge can be estimated by introducing a factor known as coefficient of discharge (C_d) such that

$$C_d$$
 or $K = \frac{Q}{Q_{th}}$

Thus

US,

$$\mathbf{Q} = C_d \frac{a_1 a_2 \sqrt{2gh}}{\sqrt{a_1^2 - a_2^2}}$$
Constant of
Venturi meter

$$C = \frac{a_1 a_2 \sqrt{2g}}{\sqrt{a_1^2 - a_2^2}}$$

$$Q = C_d C \sqrt{h}$$

Value of Cd for Venturi ranges between 0.95 to 0.98

Venturi Meter with U-tube manometer



Venturi Meter - Inclined

Bernoulli's Equation between 1 and 2

$$\frac{p_1}{w} + \frac{V_1^2}{2g} + z_1 = \frac{p_2}{w} + \frac{V_2^2}{2g} + z_2$$

$$\left(\frac{p_1}{w} + z_1\right) - \left(\frac{p_2}{w} + z_2\right) = \frac{V_2^2}{2g} - \frac{V_1^2}{2g}$$

$$h = \frac{V_2^2}{2g} - \frac{V_1^2}{2g} \longrightarrow \mathbf{Q} = C_d \frac{a_1 a_2 \sqrt{2gh}}{\sqrt{a_1^2 - a_2^2}}$$

Manometric equation

$$\frac{p_1}{w} + (z_1 - z_2) + y + x = \frac{p_2}{w} + x \left(\frac{S_m}{S}\right)$$

$$\left(\frac{p_1}{w} + z_1\right) - \left(\frac{p_2}{w} + z_2\right) = h = x\left(\frac{S_m}{S} - 1\right)$$

Thus with any position the h may be determined by noting x

The vertical position with flow upward is preferred, why



Orifice Meter

•Another device for discharge measurement, works on same principle

•Cheaper arrangement for discharge measurement



□It consists of a circular flat plate with a hole concentric with pipe

□Thickness is 0.05d, edge flat for 0.02d and beveled for 0.03d

Orifice Meter

Apply Bernoulli's

Thus,

$$h = \frac{V_2^2}{2g} - \frac{V_1^2}{2g}$$
 $V_2 = (2gh + V_1^2)^{1/2}$ Theoretical velocity

If the losses are considered

$$V_2 = C_v (2gh + V_1^2)^{1/2}$$

 C_v is the coefficient of velocity

Continuity equation gives

$$Q = a_1 V_1 = a_2 V_2$$

The area of jet a_2 and area of orifice a_0 may be given as

$$a_2 = C_c a_o$$

Orifice Meter

Solving for V_2 gives

$$V_{2} = C_{v} \left\{ \frac{2gh}{1 - C_{v}^{2}C_{c}^{2}(a_{o}^{2} / a_{1}^{2})} \right\}^{1/2}$$

$$Q = a_2 V_2 = C_c a_o V_2 \text{ and } C_c C_v = C_d$$

$$Q = \frac{C_d a_o (2gh)^{1/2}}{\left\{1 - C_d^2 (a_o^2 / a_1^2)\right\}^{1/2}}$$

Where C_d is coefficient of discharge

Its usual practice to use a simple expression such that

This equation has the same form as Venturi meter

Nozzle Meter



Rota Meter





Sample photographs



Elbow Meter



$$Q = C_d A \sqrt{2gh}$$

Pitot Tube



□Simple device for velocity measurement

Principle – if velocity of flow at a point is reduced to zero (stagnation point), the pressure there is increased due to conversion of KE into pressure energy
 By measuring this pressure rise the velocity at a point can be determined

Bernoulli's Equation between points 1 and A gives

$$h_o + \frac{V^2}{2g} = h_o + h \longrightarrow$$

$$V = \sqrt{2gh}$$

h_o is the static head and h is the dynamic head

Dynamic pressure head is proportional to a square of velocity

Pitot Tube



□If the losses are considered the velocity is given as

$$V = C\sqrt{2gh}$$

Where C is the coefficient of pitot tube and is around 0.98



Thus, $V = \sqrt{2gh}$ $V_{act} = C\sqrt{2gh}$

Pitot Tube



Commercial Pitot Tube



Commercial Pitot Tube



Flow through Orifices



Classification of orifices

- Size small, large (beyond 5cm diameter)
- Shape Circular, rectangular, square and triangular
- Upstream edge sharp edged, Bell mouthed or with round corner
- Discharge conditions Free discharging

Submerged

Fully submerged

Partially submerged



Apply BE between 1 and 2

$$\frac{p_1}{w} + \frac{V_1^2}{2g} + z_1 = \frac{p_2}{w} + \frac{V_2^2}{2g} + 0$$

V1 is the velocity of approach as the fluid approaches the orifice with this velocity

 $V_2^2 = V_1^2 + 2gh$

Due to hydrostatic conditions

$$p_1 = p_a + w(h - z_1)$$
 and $p_2 = p_a$

Thus,
$$\frac{p_a + w(h - z_1)}{w} + \frac{V_1^2}{2g} + z_1 = \frac{p_a}{w} + \frac{V_2^2}{2g} \quad \Longrightarrow \quad \frac{V_2^2}{2g} = \frac{V_1^2}{2g} + h$$

Continuity Equation $Q = a_1 V_1 = a_c V_2$

 V_1 can be assumed to be very small compared to V_2

$$V_2 = \sqrt{2gh} \quad \text{Torricelli's formula}$$

$$V = C_v \sqrt{2gh} \quad \text{Where} \quad C_v = \frac{V}{V_{th}} \quad \text{Varies between 0.95 - 0.99}$$
Coefficient of contraction may be defined as $C_c = \frac{a_c}{a}$ a is area of orifice a_c is area at VC

For bell mouthed orifice $C_c = 1$

$$C_d = \frac{Q_a}{Q_{th}}$$

$$Q_a = (a_c V) = C_c a \times C_v \sqrt{2gh}$$

$$Q_{th} = a\sqrt{2gh}$$



Thus, $Q_{act} = C_d a \sqrt{2gh}$

Flow through Large Rectangular Orifice



Flow through Large Rectangular Orifice



$$Q = C_v b_c \sqrt{2g} \times \int_{(H_c - d_c/2)}^{H_c + d_c/2} h^{1/2} dh$$

$$Q = \frac{2}{3}C_{v}b_{c}\sqrt{2g} \times \left\{ \left(H_{c} + \frac{d_{c}}{2}\right)^{3/2} - \left(H_{c} - \frac{d_{c}}{2}\right)^{3/2} \right\}$$

 H_c , b_c or d_c are difficult to determine

$$Q = \frac{2}{3}C_{c}C_{v}b\sqrt{2g} \times \left\{ \left(H + \frac{d}{2}\right)^{3/2} - \left(H - \frac{d}{2}\right)^{3/2} \right\}$$
$$Q = \frac{2}{3}C_{d}b\sqrt{2g} \times \left\{ \left(H + \frac{d}{2}\right)^{3/2} - \left(H - \frac{d}{2}\right)^{3/2} \right\}$$

In terms of H₁ and H₂ $Q = \frac{2}{3}C_d b \sqrt{2g} \times \left\{ H_2^{3/2} - H_1^{3/2} \right\}$

For large orifice
$$Q = C_d b d \sqrt{2gH}$$

Flow through Large Rectangular Orifice

If velocity of approach is considered

$$Q = \frac{2}{3}C_d b \sqrt{2g} \times \left\{ (H_2^{3/2} + V_1^2 / 2) - (H_1^{3/2} + V_1^2 / 2) \right\}$$

Flow through Large Circular Orifice



Vel. of flow through strip = $C_v \sqrt{2g(H_c - x)}$

Flow through Large Circular Orifice

Discharge through strip
$$dQ = C_v \sqrt{2g(H_c - x)} \left\{ 2\sqrt{(d_c/2)^2 - x^2} \right\} \times dx$$

$$(H_c - x)^{1/2} = H_c^{1/2} - \frac{H_c^{-1/2}x}{2} - \frac{H_c^{-3/2}x^2}{8} - \frac{H_c^{-5/2}x^3}{16} - \dots$$
 using binominal theorem

Thus,
$$dQ = 2C_v \sqrt{2g} \left[(H_c - x)^{1/2} = H_c^{1/2} - \frac{H_c^{-1/2}x}{2} - \frac{H_c^{-3/2}x^2}{8} - \frac{H_c^{-5/2}x^3}{16} - \dots \right] dx$$

On integrating by varying x between $(+d_c/2)$ to $(-d_c/2)$

$$Q = C_v \frac{\pi d_c^2}{4} \sqrt{2gH} \left[1 - \frac{d_c^2}{128H_c^2} - \frac{d_c^4}{1638H_c^4} - \dots \right]$$
$$Q = C_c C_v \frac{\pi d^2}{4} \sqrt{2gH} \left[1 - \frac{d^2}{128H^2} - \frac{d^4}{1638H^4} - \dots \right]$$
$$Q = C_d \frac{\pi d^2}{4} \sqrt{2gH} \left[1 - \frac{d^2}{128H^2} - \frac{d^4}{1638H^4} - \dots \right]$$

Flow through Large Circular Orifice

For small orifice the quantity in bracket is less than unity and the actual discharge can be given by

$$Q = C_d \, \frac{\pi d^2}{4} \sqrt{2gH}$$

Determination of C_v of freely discharging Orifice



Totally submerged orifice



 $Q = C_d a \sqrt{2gH}$

Partially submerged orifice



Notches and Wiers



Nappe or vein

➢Notch - An opening provided in the side of the tank such that liquid surface in the tank is below the top edge of the opening

>Notches made up of metallic plates are provided in narrow channels to measure the rate of flow

➢Weir – Concrete or masonry structure built across the river to raise the level of water on the upstream side and allow the excess water to flow over the entire length to the downstream side

Similar to small dam

Notches and Wiers



V Notch Weir







Notches

According to shape – Rectangular, triangular, trapezoidal, parabolic and stepped

□According to effect of sides on nappe –

1. Notch with end contraction 2. Notch without end contraction or

suppressed notch

Wiers

□According to shape – Rectangular, triangular, trapezoidal

According to shape of crest – Sharp crested weir, narrow crested weir broad crested, ogee shaped

□According to effect of sides on nappe –

1. Notch with end contraction 2. Notch without end contraction or suppressed notch
Flow over Rectangular Sharp Crested Weir or Notch





Nappe or vein

Consider the elemental strip of thickness dh at a distance of h from free surface

Area of strip = $L \times dh$

Velocity of fluid = $\sqrt{2gh}$

$$dQ = C_d \times L \times dh \times \sqrt{2gh}$$

$$Q = \int_{0}^{H} C_{d} \times L \times dh \times \sqrt{2gh}$$

$$Q = \frac{2}{3}C_d \times L \times \sqrt{2g} \times H^{3/2}$$



Flow over Rectangular Sharp Crested Weir or Notch



If velocity of approach = V_a , the corresponding head is given as

$$h_a = \frac{V_a^2}{2g}$$

The limits of integration will be h_a to H+h_a

Thus

$$Q = \int_{h_a}^{H+h_a} C_d \times L \times \sqrt{2gh} \times dh$$

$$Q = \frac{2}{3}C_{d} \times L \times \sqrt{2g} \times \left[(H + h_{a})^{3/2} - h_{a}^{3/2} \right]$$

H+h_a is known as still water head

The above equation is applicable to suppressed weir or notch for which crest length is equal to the width of channel

Notch with end contraction



End contraction - reduces effective crest length – contraction of nappe – less discharge



Notch with end contraction

$$Q = \frac{2}{3}C_d \times \sqrt{2g} \times (L - 0.1H) \times H^{3/2} \text{ - without } V_a$$

$$Q = \frac{2}{3}C_d \times \sqrt{2g} \times (L - 0.1H_1) \times \left[(H_1)^{3/2} - h_a^{3/2} \right] - \text{with } V_a$$

Where,
$$H_1 = (H + h_a) = (H + V_a^2 / 2g)$$

>Mean value of velocity of approach, Va is given as

$$V_a = \frac{Q}{B(H+Z)}$$

for the case with end contraction

$$V_a = \frac{Q}{L(H+Z)}$$

for the case of suppressed weir or notch

Triangular Notch





Triangular Notch



Hence

$$Q = 2C_d \sqrt{2g} \tan \frac{\theta}{2} \int_{0}^{H} (H-h)h^{1/2} dh$$

$$Q = 2C_d \sqrt{2g} \tan \frac{\theta}{2} \left[\frac{2}{3} H h^{3/2} - \frac{2}{5} h^{5/2} \right]_0^H$$

$$Q = \frac{8}{15} C_d \sqrt{2g} \tan \frac{\theta}{2} H^{5/2}$$

For $\theta = 90^{\circ} Q = \frac{8}{15} C_d \sqrt{2g} H^{5/2}$ If C_d is assumed to be 0.6 $Q = 1.418 H^{5/2}$

If velocity of approach is considered

$$Q = \frac{8}{15} C_d \sqrt{2g} \tan \frac{\theta}{2} \left[(H + h_a)^{5/2} - h_a^{5/2} \right] \quad \text{where,} \quad h_a = \frac{V_a^2}{2g}$$

Navier-Stokes Equation

X-momentum equation for laminar flow of an incompressible flow



Vector form or coordinatedfree form of N-S equationd

$$\frac{\partial V}{\partial t} + V \cdot \nabla V = -\frac{1}{\rho} \nabla p + \frac{\mu}{\rho} \nabla^2 V$$

Complete N-S Equation

A note on Navier-Stokes Equation



- The N-S equation is used for analyzing the laminar flow
- There is a viscous term in N-S equation apart from the terms in Euler equation
- The viscous term represents the shear forces acting on the fluid particle
- Analytical solution of this equation for 2D and 3D is not possible
- Obtaining the numerical solution of this equation in combination with continuity equation is an important aspect of computational fluid dynamics

Static, Dynamic and Stagnation Pressure





Each term in the above equation has pressure units and thus each term represents some kind of pressure

- > p is the static pressure; it represents the actual thermodynamic pressure
- > $\rho V^2/2$ is the dynamic pressure; it represents the pressure rise when the fluid in motion is brought to rest isentropically
- > pgz is the hydrostatic pressure; it accounts for elevation effects

$$p + \rho \frac{V^2}{2}$$
 represents the stagnation pressure

Diagrammatic Representation of static, dynamic and stagnation pressure





Calculate the kinetic energy correction factor α for the following velocity distributions in a circular pipe of radius r_0 .

$$1. \quad \frac{u}{u_m} = \left(1 - \frac{r}{r_o}\right)$$

2.
$$\frac{u}{u_m} = \left[1 - (r/r_o)^2\right]$$

PROBLEM 2



215 liters of gasoline (specific gravity 0.82) flow per second upward in an inclined Venturi meter fitted to a 300 mm diameter pipe. The Venturi meter is inclined at 60° to the vertical and its 150 mm diameter throat is 1.2 m from the entrance along its length. Pressure gages inserted at the entrance and throat show pressures of 0.141 N/mm² and 0.077 N/mm² respectively. Calculate the discharge coefficient of the Venturi meter.

If instead of pressure gages the entrance and throat are connected to the two limb U-tube mercury manometer, determine its reading in mm of differential mercury column.



The pressure leads from a Pitot-tube mounted on an air craft are connected to a pressure gage in the cockpit. The dial of the pressure gage is calibrated to read the speed in m/s.

The calibration is done on the ground by applying a known pressure across the gage and calculating the equivalent velocity using incompressible Bernoulli's equation and assuming that the density is 1.224 kg/m³

The gage having been calibrated in this way the air craft is flown at 9200 m, where the density is 0.454 kg/m³ and ambient pressure is 30000 N/m². The gage indicates the velocity of 152 m/s. What is the true speed of the air craft?